

Three nucleon scattering in a “three dimensional” approach

Kacper Topolnicki
Jacek Golak
Roman Skibiński
Henryk Witała

August 12, 2016



1 PWD VS 3D

- “CLASSICAL” APPROACH
- 3D APPROACH

2 GENERAL OPERATOR FORM

- ROTATIONS
- OTHER SYMMETRIES

3 3N SCATTERING

- CONVERGENCE

4 SUMMARY

PARTIAL WAVES - EXAMPLE

- For the moment let's focus on the 2N system.
- Let's try to calculate the 2N transition operator.

PARTIAL WAVES - SYMMETRIZATION

- \check{V} is the 2N potential.
- Each \blacksquare lives in a subspace with given orbital angular momentum l , spin s and total angular momentum j and different momentum magnitude states:

$$\langle |\mathbf{p}'|(l's')j' | \dots | |\mathbf{p}|(ls)j \rangle$$

- Impose parity, time reversal and rotational symmetry ...

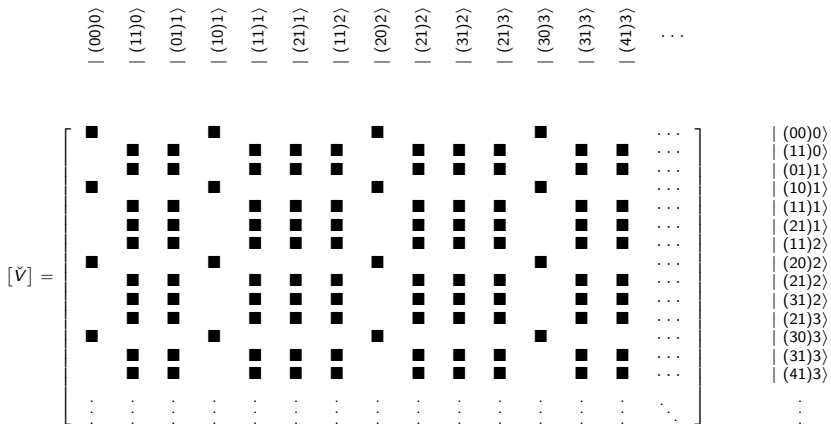
PARTIAL WAVES - SYMMETRIZATION

- \check{V} is the 2N potential.
- Each \blacksquare lives in a subspace with given orbital angular momentum l , spin s and total angular momentum j and different momentum magnitude states:

$$\langle |\mathbf{p}'| (l' s') j' | \dots | |\mathbf{p}| (l s) j \rangle$$

- Impose parity, time reversal and rotational symmetry ...

PARTIAL WAVES - SYMMETRIZATION



PARTIAL WAVES - CALCULATION

- Perform PWD on each operator of, eg., LSE $\check{t} = \check{V} + \check{V}\check{G}_0\check{t}$.
- Solve the resulting linear equations.

PARTIAL WAVES - CALCULATION

- Perform PWD on each operator of, eg., LSE $\check{t} = \check{V} + \check{V}\check{G}_0\check{t}$.
- Solve the resulting linear equations.

PARTIAL WAVES - CALCULATION

- Perform PWD on each operator of, eg., LSE $\check{t} = \check{V} + \check{V}\check{G}_0\check{t}$.
- Solve the resulting linear equations.

PARTIAL WAVES - PROS AND CONS

- +
 - Battle tested.
 - Small numerical workload.
- —
 - Implementation requires heavily oscillating functions.
 - It is not always obvious how many partial waves need to be taken into account.
 - This is more complicated for three or more particles and different coupling schemes.
 - Convergence problems for higher energies.

PARTIAL WAVES - PROS AND CONS

- +
 - Battle tested.
 - Small numerical workload.
- —
 - Implementation requires heavily oscillating functions.
 - It is not always obvious how many partial waves need to be taken into account.
 - This is more complicated for three or more particles and different coupling schemes.
 - Convergence problems for higher energies.

PARTIAL WAVES - PROS AND CONS

- +
 - Battle tested.
 - Small numerical workload.
- —
 - Implementation requires heavily oscillating functions.
 - It is not always obvious how many partial waves need to be taken into account.
 - This is more complicated for three or more particles and different coupling schemes.
 - Convergence problems for higher energies.

PARTIAL WAVES - PROS AND CONS

- +
 - Battle tested.
 - Small numerical workload.
- —
 - Implementation requires heavily oscillating functions.
 - It is not always obvious how many partial waves need to be taken into account.
 - This is more complicated for three or more particles and different coupling schemes.
 - Convergence problems for higher energies.

PARTIAL WAVES - PROS AND CONS

- +
 - Battle tested.
 - Small numerical workload.
- —
 - Implementation requires heavily oscillating functions.
 - It is not always obvious how many partial waves need to be taken into account.
 - This is more complicated for three or more particles and different coupling schemes.
 - Convergence problems for higher energies.

3D - EXAMPLE

- Lets take the 2N transition operator.
- Assume we are working in momentum space with $\mathbf{p}' = (p'_x, p'_y, p'_z)$ being the final and $\mathbf{p} = (p_x, p_y, p_z)$ being the initial momentum of the two nucleons.

3D - EXAMPLE

- Lets take the 2N transition operator.
- Assume we are working in momentum space with $\mathbf{p}' = (p'_x, p'_y, p'_z)$ being the final and $\mathbf{p} = (p_x, p_y, p_z)$ being the initial momentum of the two nucleons.

3D - EXAMPLE

- Lets take the 2N transition operator.
- Assume we are working in momentum space with $\mathbf{p}' = (p'_x, p'_y, p'_z)$ being the final and $\mathbf{p} = (p_x, p_y, p_z)$ being the initial momentum of the two nucleons.

3D - EXAMPLE

- Lets take the 2N transition operator.
- Assume we are working in momentum space with $\mathbf{p}' = (p'_x, p'_y, p'_z)$ being the final and $\mathbf{p} = (p_x, p_y, p_z)$ being the initial momentum of the two nucleons.

3D - SIZE OF THE PROBLEM

- We would like to calculate the full transition operator. This is equivalent to calculating, for every \mathbf{p}' and every \mathbf{p} , the matrix element $\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle$.
- This matrix element is an operator in spin space and has the form:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \begin{bmatrix} t_{11}(p'_x, p'_y, p'_z, p_x, p_y, p_z) & t_{12}(\dots) & t_{13}(\dots) & t_{14}(\dots) \\ t_{21}(\dots) & t_{22}(\dots) & t_{23}(\dots) & t_{24}(\dots) \\ t_{31}(\dots) & t_{32}(\dots) & t_{33}(\dots) & t_{34}(\dots) \\ t_{41}(\dots) & t_{42}(\dots) & t_{43}(\dots) & t_{44}(\dots) \end{bmatrix}.$$

- It must satisfy the LSE equation $\check{t} = \check{V} + \check{V} \check{G}_0 \check{t}$.

3D - SIZE OF THE PROBLEM

- We would like to calculate the full transition operator. This is equivalent to calculating, for every \mathbf{p}' and every \mathbf{p} , the matrix element $\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle$.
- This matrix element is an operator in spin space and has the form:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \begin{bmatrix} t_{11}(p'_x, p'_y, p'_z, p_x, p_y, p_z) & t_{12}(\dots) & t_{13}(\dots) & t_{14}(\dots) \\ t_{21}(\dots) & t_{22}(\dots) & t_{23}(\dots) & t_{24}(\dots) \\ t_{31}(\dots) & t_{32}(\dots) & t_{33}(\dots) & t_{34}(\dots) \\ t_{41}(\dots) & t_{42}(\dots) & t_{43}(\dots) & t_{44}(\dots) \end{bmatrix}.$$

- It must satisfy the LSE equation $\check{t} = \check{V} + \check{V} \check{G}_0 \check{t}$.

3D - SIZE OF THE PROBLEM

- We would like to calculate the full transition operator. This is equivalent to calculating, for every \mathbf{p}' and every \mathbf{p} , the matrix element $\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle$.
- This matrix element is an operator in spin space and has the form:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \begin{bmatrix} t_{11}(p'_x, p'_y, p'_z, p_x, p_y, p_z) & t_{12}(\dots) & t_{13}(\dots) & t_{14}(\dots) \\ t_{21}(\dots) & t_{22}(\dots) & t_{23}(\dots) & t_{24}(\dots) \\ t_{31}(\dots) & t_{32}(\dots) & t_{33}(\dots) & t_{34}(\dots) \\ t_{41}(\dots) & t_{42}(\dots) & t_{43}(\dots) & t_{44}(\dots) \end{bmatrix}.$$

- It must satisfy the LSE equation $\check{t} = \check{V} + \check{V} \check{G}_0 \check{t}$.

3D - SIZE OF THE PROBLEM

- We would like to calculate the full transition operator. This is equivalent to calculating, for every \mathbf{p}' and every \mathbf{p} , the matrix element $\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle$.
- This matrix element is an operator in spin space and has the form:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \begin{bmatrix} t_{11}(p'_x, p'_y, p'_z, p_x, p_y, p_z) & t_{12}(\dots) & t_{13}(\dots) & t_{14}(\dots) \\ t_{21}(\dots) & t_{22}(\dots) & t_{23}(\dots) & t_{24}(\dots) \\ t_{31}(\dots) & t_{32}(\dots) & t_{33}(\dots) & t_{34}(\dots) \\ t_{41}(\dots) & t_{42}(\dots) & t_{43}(\dots) & t_{44}(\dots) \end{bmatrix}.$$

- It must satisfy the LSE equation $\check{t} = \check{V} + \check{V} \check{G}_0 \check{t}$.

3D - SIZE OF THE PROBLEM

- We need to calculate 16 functions of 6 real parameters that satisfy the LSE.
- We know that the solution has to satisfy appropriate symmetries.
- Can we use this to simplify the problem?

3D - SIZE OF THE PROBLEM

- We need to calculate 16 functions of 6 real parameters that satisfy the LSE.
- We know that the solution has to satisfy appropriate symmetries.
- Can we use this to simplify the problem?

3D - SIZE OF THE PROBLEM

- We need to calculate 16 functions of 6 real parameters that satisfy the LSE.
- We know that the solution has to satisfy appropriate symmetries.
- Can we use this to simplify the problem?

3D - SIZE OF THE PROBLEM

- We need to calculate 16 functions of 6 real parameters that satisfy the LSE.
- We know that the solution has to satisfy appropriate symmetries.
- Can we use this to simplify the problem?

3D - SIZE OF THE PROBLEM

- We need to calculate 16 functions of 6 real parameters that satisfy the LSE.
- We know that the solution has to satisfy appropriate symmetries.
- Can we use this to simplify the problem?

3D - SYMMETRIZATION

- The general operator form of the two nucleon potential and transition operator is well known [Phys. Rev. 96 1654 (1954)].
- The matrix element in momentum space can be written as a linear combination of 6 scalar functions t_i and spin operators $[w_i]$:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \sum_{i=1}^6 t_i(|\mathbf{p}'|, |\mathbf{p}|, \hat{\mathbf{p}}' \cdot \hat{\mathbf{p}}) [w_i(\mathbf{p}, \mathbf{p})].$$

- Instead of calculating 16 functions of 6 real variables we now only need to calculate 6 functions of 3 variables.
- Couple orders of magnitude less numerical work!

3D - SYMMETRIZATION

- The general operator form of the two nucleon potential and transition operator is well known [Phys. Rev. 96 1654 (1954)].
- The matrix element in momentum space can be written as a linear combination of 6 scalar functions t_i and spin operators $[w_i]$:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \sum_{i=1}^6 t_i(|\mathbf{p}'|, |\mathbf{p}|, \hat{\mathbf{p}}' \cdot \hat{\mathbf{p}}) [w_i(\mathbf{p}, \mathbf{p})].$$

- Instead of calculating 16 functions of 6 real variables we now only need to calculate 6 functions of 3 variables.
- Couple orders of magnitude less numerical work!

3D - SYMMETRIZATION

- The general operator form of the two nucleon potential and transition operator is well known [Phys. Rev. 96 1654 (1954)].
- The matrix element in momentum space can be written as a linear combination of 6 scalar functions t_i and spin operators $[w_i]$:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \sum_{i=1}^6 t_i(|\mathbf{p}'|, |\mathbf{p}|, \hat{\mathbf{p}}' \cdot \hat{\mathbf{p}}) [\check{w}_i(\mathbf{p}, \mathbf{p})].$$

- Instead of calculating 16 functions of 6 real variables we now only need to calculate 6 functions of 3 variables.
- Couple orders of magnitude less numerical work!

3D - SYMMETRIZATION

- The general operator form of the two nucleon potential and transition operator is well known [Phys. Rev. 96 1654 (1954)].
- The matrix element in momentum space can be written as a linear combination of 6 scalar functions t_i and spin operators $[w_i]$:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \sum_{i=1}^6 t_i(|\mathbf{p}'|, |\mathbf{p}|, \hat{\mathbf{p}}' \cdot \hat{\mathbf{p}}) [\check{w}_i(\mathbf{p}, \mathbf{p})].$$

- Instead of calculating 16 functions of 6 real variables we now only need to calculate 6 functions of 3 variables.
- Couple orders of magnitude less numerical work!

3D - SYMMETRIZATION

- The general operator form of the two nucleon potential and transition operator is well known [Phys. Rev. 96 1654 (1954)].
- The matrix element in momentum space can be written as a linear combination of 6 scalar functions t_i and spin operators $[w_i]$:

$$[\langle \mathbf{p}' | \check{t} | \mathbf{p} \rangle] = \sum_{i=1}^6 t_i(|\mathbf{p}'|, |\mathbf{p}|, \hat{\mathbf{p}}' \cdot \hat{\mathbf{p}}) [\check{w}_i(\mathbf{p}, \mathbf{p})].$$

- Instead of calculating 16 functions of 6 real variables we now only need to calculate 6 functions of 3 variables.
- Couple orders of magnitude less numerical work!

3D - PROS AND CONS

- +
 - More precision at higher energies.
 - Calculations can be easily modified to use different potentials.
 - Operator forms (operators and states) significantly reduce numerical workload.

- —
 - We are running out of operator forms!
 - **Can we construct new symmetric operator forms? Can this be generalized to systems of three or more particles?**

3D - PROS AND CONS

- +
 - More precision at higher energies.
 - Calculations can be easily modified to use different potentials.
 - Operator forms (operators and states) significantly reduce numerical workload.

- —
 - We are running out of operator forms!
 - **Can we construct new symmetric operator forms? Can this be generalized to systems of three or more particles?**

3D - PROS AND CONS

- +
 - More precision at higher energies.
 - Calculations can be easily modified to use different potentials.
 - Operator forms (operators and states) significantly reduce numerical workload.

- —
 - We are running out of operator forms!
 - Can we construct new symmetric operator forms? Can this be generalized to systems of three or more particles?

3D - PROS AND CONS

- +
 - More precision at higher energies.
 - Calculations can be easily modified to use different potentials.
 - Operator forms (operators and states) significantly reduce numerical workload.
- —
 - We are running out of operator forms!
 - Can we construct new symmetric operator forms? Can this be generalized to systems of three or more particles?

3D - PROS AND CONS

- +
 - More precision at higher energies.
 - Calculations can be easily modified to use different potentials.
 - Operator forms (operators and states) significantly reduce numerical workload.
- —
 - We are running out of operator forms!
 - Can we construct new symmetric operator forms? Can this be generalized to systems of three or more particles?

3D - PROS AND CONS

- +
 - More precision at higher energies.
 - Calculations can be easily modified to use different potentials.
 - Operator forms (operators and states) significantly reduce numerical workload.

- —
 - We are running out of operator forms!
 - **Can we construct new symmetric operator forms? Can this be generalized to systems of three or more particles?**

INVARIANCE UNDER SPATIAL ROTATIONS

- If \check{R} is a spatial rotation, we require that operator \check{X} :

$$\check{R}^{-1}\check{X}\check{R} = \check{X}.$$

- Ideally we would like to fit the operator into an operator form:

$$\langle \dots | \check{X} | \dots \rangle = \sum x_i [\check{O}_i].$$

Here x is a scalar function of momenta and O is an operator in spin space and \dots are momenta.

- How can a rotation invariant operator be constructed?

INVARIANCE UNDER SPATIAL ROTATIONS

- If \check{R} is a spatial rotation, we require that operator \check{X} :

$$\check{R}^{-1}\check{X}\check{R} = \check{X}.$$

- Ideally we would like to fit the operator into an operator form:

$$\langle \dots | \check{X} | \dots \rangle = \sum x_i [\check{O}_i].$$

Here x is a scalar function of momenta and O is an operator in spin space and \dots are momenta.

- How can a rotation invariant operator be constructed?

INVARIANCE UNDER SPATIAL ROTATIONS

- If \check{R} is a spatial rotation, we require that operator \check{X} :

$$\check{R}^{-1}\check{X}\check{R} = \check{X}.$$

- Ideally we would like to fit the operator into an operator form:

$$\langle \dots | \check{X} | \dots \rangle = \sum x_i [\check{O}_i].$$

Here x is a scalar function of momenta and O is an operator in spin space and \dots are momenta.

- How can a rotation invariant operator be constructed?

INVARIANCE UNDER SPATIAL ROTATIONS

- If \check{R} is a spatial rotation, we require that operator \check{X} :

$$\check{R}^{-1}\check{X}\check{R} = \check{X}.$$

- Ideally we would like to fit the operator into an operator form:

$$\langle \dots | \check{X} | \dots \rangle = \sum x_i [\check{O}_i].$$

Here x is a scalar function of momenta and O is an operator in spin space and \dots are momenta.

- How can a rotation invariant operator be constructed?

INVARIANCE UNDER SPATIAL ROTATIONS

- Let's generalize a little bit and incorporate the dependance on the total momentum \mathbf{K} .
- Boulding blocks (actually any number of momenta and spin vectors can be used):

$$\mathbb{T} = \{\check{\mathbf{p}}', \check{\mathbf{p}}, \check{\mathbf{K}}, \check{\sigma}(1), \check{\sigma}(2)\}.$$

- In principle we have to consider all scalar combinations of the elements from \mathbb{T} . For example if $\check{\mathbf{v}}_i \in \mathbb{T}$ we could use:

$$(\check{\mathbf{v}}_1 \times (\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_3)) \cdot (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times (\check{\mathbf{v}}_6 \times \check{\mathbf{v}}_7)))$$

or

$$(\check{\mathbf{v}}_1 \times \check{\mathbf{v}}_2) \cdot (\check{\mathbf{v}}_3 \times (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times \check{\mathbf{v}}_6))).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- Let's generalize a little bit and incorporate the dependance on the total momentum \mathbf{K} .
- Boulding blocks (actually any number of momenta and spin vectors can be used):

$$\mathbb{T} = \{\check{\mathbf{p}}', \check{\mathbf{p}}, \check{\mathbf{K}}, \check{\sigma}(1), \check{\sigma}(2)\}.$$

- In principle we have to consider all scalar combinations of the elements from \mathbb{T} . For example if $\check{\mathbf{v}}_i \in \mathbb{T}$ we could use:

$$(\check{\mathbf{v}}_1 \times (\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_3)) \cdot (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times (\check{\mathbf{v}}_6 \times \check{\mathbf{v}}_7)))$$

or

$$(\check{\mathbf{v}}_1 \times \check{\mathbf{v}}_2) \cdot (\check{\mathbf{v}}_3 \times (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times \check{\mathbf{v}}_6))).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- Let's generalize a little bit and incorporate the dependance on the total momentum \mathbf{K} .
- Boulding blocks (actually any number of momenta and spin vectors can be used):

$$\mathbb{T} = \{\check{\mathbf{p}}', \check{\mathbf{p}}, \check{\mathbf{K}}, \check{\sigma}(1), \check{\sigma}(2)\}.$$

- In principle we have to consider all scalar combinations of the elements from \mathbb{T} . For example if $\check{\mathbf{v}}_i \in \mathbb{T}$ we could use:

$$(\check{\mathbf{v}}_1 \times (\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_3)) \cdot (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times (\check{\mathbf{v}}_6 \times \check{\mathbf{v}}_7)))$$

or

$$(\check{\mathbf{v}}_1 \times \check{\mathbf{v}}_2) \cdot (\check{\mathbf{v}}_3 \times (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times \check{\mathbf{v}}_6))).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- Let's generalize a little bit and incorporate the dependance on the total momentum \mathbf{K} .
- Boulding blocks (actually any number of momenta and spin vectors can be used):

$$\mathbb{T} = \{\check{\mathbf{p}}', \check{\mathbf{p}}, \check{\mathbf{K}}, \check{\sigma}(1), \check{\sigma}(2)\}.$$

- In principle we have to consider all scalar combinations of the elements from \mathbb{T} . For example if $\check{\mathbf{v}}_i \in \mathbb{T}$ we could use:

$$(\check{\mathbf{v}}_1 \times (\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_3)) \cdot (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times (\check{\mathbf{v}}_6 \times \check{\mathbf{v}}_7)))$$

or

$$(\check{\mathbf{v}}_1 \times \check{\mathbf{v}}_2) \cdot (\check{\mathbf{v}}_3 \times (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times \check{\mathbf{v}}_6))).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- Simple vector identities lead to:

$$\begin{aligned}
 & (\check{\mathbf{v}}_1 \times (\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_3)) \cdot (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times (\check{\mathbf{v}}_6 \times \check{\mathbf{v}}_7))) \\
 &= (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_3 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7) \\
 &\quad + (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_3 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7)
 \end{aligned}$$

and

$$\begin{aligned}
 & (\check{\mathbf{v}}_1 \times \check{\mathbf{v}}_2) \cdot (\check{\mathbf{v}}_3 \times (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times \check{\mathbf{v}}_6))) \\
 &= (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6) \\
 &\quad + (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6).
 \end{aligned}$$

INVARIANCE UNDER SPATIAL ROTATIONS

- Simple vector identities lead to:

$$\begin{aligned}
 & (\check{\mathbf{v}}_1 \times (\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_3)) \cdot (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times (\check{\mathbf{v}}_6 \times \check{\mathbf{v}}_7))) \\
 &= (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_3 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7) \\
 &\quad + (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_3 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7)
 \end{aligned}$$

and

$$\begin{aligned}
 & (\check{\mathbf{v}}_1 \times \check{\mathbf{v}}_2) \cdot (\check{\mathbf{v}}_3 \times (\check{\mathbf{v}}_4 \times (\check{\mathbf{v}}_5 \times \check{\mathbf{v}}_6))) \\
 &= (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5) \\
 &\quad - (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6) \\
 &\quad + (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6).
 \end{aligned}$$

INVARIANCE UNDER SPATIAL ROTATIONS

- A general observation can be made: Any scalar expression constructed from operators in \mathbb{T} can be constructed from a combination of operators in the set \mathbb{V} :

$$\mathbb{V} = \{\check{1}, \check{\mathbf{v}}_i \cdot \check{\mathbf{v}}_j, (\check{\mathbf{v}}_i \times \check{\mathbf{v}}_j) \cdot \check{\mathbf{v}}_k\}.$$

- For example, from the previous slide, we have the following CHAINS of operators of length 3:

$$[\check{C}_1] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_2] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_3 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_3] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_3 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_4] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_5] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5),$$

$$[\check{C}_6] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5),$$

$$[\check{C}_7] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6),$$

$$[\check{C}_8] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- A general observation can be made: Any scalar expression constructed from operators in \mathbb{T} can be constructed from a combination of operators in the set \mathbb{V} :

$$\mathbb{V} = \{\check{1}, \check{\mathbf{v}}_i \cdot \check{\mathbf{v}}_j, (\check{\mathbf{v}}_i \times \check{\mathbf{v}}_j) \cdot \check{\mathbf{v}}_k\}.$$

- For example, from the previous slide, we have the following CHAINS of operators of length 3:

$$[\check{C}_1] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_2] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_3 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_3] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_3 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_4] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_5] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5),$$

$$[\check{C}_6] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5),$$

$$[\check{C}_7] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6),$$

$$[\check{C}_8] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- A general observation can be made: Any scalar expression constructed from operators in \mathbb{T} can be constructed from a combination of operators in the set \mathbb{V} :

$$\mathbb{V} = \{\check{1}, \check{\mathbf{v}}_i \cdot \check{\mathbf{v}}_j, (\check{\mathbf{v}}_i \times \check{\mathbf{v}}_j) \cdot \check{\mathbf{v}}_k\}.$$

- For example, from the previous slide, we have the following CHAINS of operators of length 3:

$$[\check{C}_1] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_2] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_3 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_3] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_2)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_3 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_4] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \times \check{\mathbf{v}}_6 \cdot \check{\mathbf{v}}_7),$$

$$[\check{C}_5] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5),$$

$$[\check{C}_6] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_6)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_5),$$

$$[\check{C}_7] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6),$$

$$[\check{C}_8] = (\check{\mathbf{v}}_1 \cdot \check{\mathbf{v}}_3)(\check{\mathbf{v}}_2 \cdot \check{\mathbf{v}}_5)(\check{\mathbf{v}}_4 \cdot \check{\mathbf{v}}_6).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- How get from this to the operator form?
- In principle we have to include CHAINS of operators constructed from \mathbb{V} with any number of links?

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \dots + \sum_{i=1}^8 x_i [\check{C}_i] + \dots$$

- Infinitely many terms?

INVARIANCE UNDER SPATIAL ROTATIONS

- How get from this to the operator form?
- In principle we have to include CHAINS of operators constructed from \mathbb{V} with any number of links?

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \dots + \sum_{i=1}^8 x_i [\check{C}_i] + \dots$$

- Infinitely many terms?

INVARIANCE UNDER SPATIAL ROTATIONS

- How get from this to the operator form?
- In principle we have to include CHAINS of operators constructed from \mathbb{V} with any number of links?

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \dots + \sum_{i=1}^8 x_i [\check{C}_i] + \dots$$

- Infinitely many terms?

INVARIANCE UNDER SPATIAL ROTATIONS

- How get from this to the operator form?
- In principle we have to include CHAINS of operators constructed from \mathbb{V} with any number of links?

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \dots + \sum_{i=1}^8 x_i [\check{C}_i] + \dots$$

- Infinitely many terms?

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{W}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{W}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- Not all chains are unique. $[\check{C}_i]$ not unique if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$.
- The algorithm in [*Eur. Phys. J. A* 52:188 (2016)] can be summarized:
 - Start with all chains of length 1.
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta (eliminate $[\check{C}_i]$ if $[\check{C}_i] = \sum_{j \neq i} c_j [\check{C}_j]$).
 - Consider all chains of length 2 (for example by multiplying the reduced set from the previous iteration by all operators from \mathbb{V}).
 - Eliminate from this set those chains that are expressible by others via a linear combination with scalar functions of momenta.
 - ...
 - At some point adding further links to the chains does not add any new unique operators.
 - We end up with a finite number of operators and a a general rotation invariant form.

INVARIANCE UNDER SPATIAL ROTATIONS

- After the first iteration 11 unique chains of length 1:

$$\begin{array}{l}
 \dot{\mathbf{i}} \\
 \dot{\mathbf{p}}' \cdot \check{\sigma}(1) \\
 \dot{\mathbf{p}}' \cdot \check{\sigma}(2) \\
 \dot{\mathbf{p}} \cdot \check{\sigma}(1) \\
 \dot{\mathbf{p}} \cdot \check{\sigma}(2) \\
 \check{\mathbf{K}} \cdot \check{\sigma}(1) \\
 \check{\mathbf{K}} \cdot \check{\sigma}(2) \\
 \check{\sigma}(1) \cdot \check{\sigma}(2) \\
 (\dot{\mathbf{p}}' \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 (\dot{\mathbf{p}} \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 (\check{\mathbf{K}} \times \check{\sigma}(1)) \cdot \check{\sigma}(2).
 \end{array}$$

INVARIANCE UNDER SPATIAL ROTATIONS

- After the first iteration 11 unique chains of length 1:

$$\begin{aligned}
 & \check{i} \\
 & \check{p}' \cdot \check{\sigma}(1) \\
 & \check{p}' \cdot \check{\sigma}(2) \\
 & \check{p} \cdot \check{\sigma}(1) \\
 & \check{p} \cdot \check{\sigma}(2) \\
 & \check{K} \cdot \check{\sigma}(1) \\
 & \check{K} \cdot \check{\sigma}(2) \\
 & \check{\sigma}(1) \cdot \check{\sigma}(2) \\
 & (\check{p}' \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 & (\check{p} \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 & (\check{K} \times \check{\sigma}(1)) \cdot \check{\sigma}(2).
 \end{aligned}$$

INVARIANCE UNDER SPATIAL ROTATIONS

- After the second iteration 16 independent chains of length < 2 . Since this is the last iteration, they have special names.

$$\begin{aligned}
 [\check{O}_1] &= \check{I} \\
 [\check{O}_2] &= \check{p}' \cdot \check{\sigma}(1) \\
 [\check{O}_3] &= \check{p}' \cdot \check{\sigma}(2) \\
 [\check{O}_4] &= \check{p} \cdot \check{\sigma}(1) \\
 [\check{O}_5] &= \check{p} \cdot \check{\sigma}(2) \\
 [\check{O}_6] &= \check{K} \cdot \check{\sigma}(1) \\
 [\check{O}_7] &= \check{K} \cdot \check{\sigma}(2) \\
 [\check{O}_8] &= \check{\sigma}(1) \cdot \check{\sigma}(2) \\
 [\check{O}_9] &= (\check{p}' \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 [\check{O}_{10}] &= (\check{p} \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 [\check{O}_{11}] &= (\check{K} \times \check{\sigma}(1)) \cdot \check{\sigma}(2) \\
 [\check{O}_{12}] &= (\check{p}' \cdot \check{\sigma}(1))(\check{p}' \cdot \check{\sigma}(2)) \\
 [\check{O}_{13}] &= (\check{p}' \cdot \check{\sigma}(1))(\check{p} \cdot \check{\sigma}(2)) \\
 [\check{O}_{14}] &= (\check{p}' \cdot \check{\sigma}(1))(\check{K} \cdot \check{\sigma}(2)) \\
 [\check{O}_{15}] &= (\check{p} \cdot \check{\sigma}(1))(\check{p} \cdot \check{\sigma}(2)) \\
 [\check{O}_{16}] &= (\check{p} \cdot \check{\sigma}(1))(\check{K} \cdot \check{\sigma}(2)).
 \end{aligned}$$

INVARIANCE UNDER SPATIAL ROTATIONS

- After the second iteration 16 independent chains of length < 2 . Since this is the last iteration, they have special names.

$$[\check{O}_1] = \check{I}$$

$$[\check{O}_2] = \check{p}' \cdot \check{\sigma}(1)$$

$$[\check{O}_3] = \check{p}' \cdot \check{\sigma}(2)$$

$$[\check{O}_4] = \check{p} \cdot \check{\sigma}(1)$$

$$[\check{O}_5] = \check{p} \cdot \check{\sigma}(2)$$

$$[\check{O}_6] = \check{K} \cdot \check{\sigma}(1)$$

$$[\check{O}_7] = \check{K} \cdot \check{\sigma}(2)$$

$$[\check{O}_8] = \check{\sigma}(1) \cdot \check{\sigma}(2)$$

$$[\check{O}_9] = (\check{p}' \times \check{\sigma}(1)) \cdot \check{\sigma}(2)$$

$$[\check{O}_{10}] = (\check{p} \times \check{\sigma}(1)) \cdot \check{\sigma}(2)$$

$$[\check{O}_{11}] = (\check{K} \times \check{\sigma}(1)) \cdot \check{\sigma}(2)$$

$$[\check{O}_{12}] = (\check{p}' \cdot \check{\sigma}(1))(\check{p}' \cdot \check{\sigma}(2))$$

$$[\check{O}_{13}] = (\check{p}' \cdot \check{\sigma}(1))(\check{p} \cdot \check{\sigma}(2))$$

$$[\check{O}_{14}] = (\check{p}' \cdot \check{\sigma}(1))(\check{K} \cdot \check{\sigma}(2))$$

$$[\check{O}_{15}] = (\check{p} \cdot \check{\sigma}(1))(\check{p} \cdot \check{\sigma}(2))$$

$$[\check{O}_{16}] = (\check{p} \cdot \check{\sigma}(1))(\check{K} \cdot \check{\sigma}(2)).$$

INVARIANCE UNDER SPATIAL ROTATIONS

- The third iteration does not introduce any new unique operators!
- We just created the operator form for \check{X} :

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \sum_{i=1}^{16} x_i [\check{O}_i(\mathbf{p}, \mathbf{p}', \mathbf{K})] .$$

- \check{X} could be the potential, transition operator with relativistic corrections ...
- The set \mathbb{T} can be extended ...

INVARIANCE UNDER SPATIAL ROTATIONS

- The third iteration does not introduce any new unique operators!
- We just created the operator form for \check{X} :

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \sum_{i=1}^{16} x_i [\check{O}_i(\mathbf{p}, \mathbf{p}', \mathbf{K})] .$$

- \check{X} could be the potential, transition operator with relativistic corrections ...
- The set \mathbb{T} can be extended ...

INVARIANCE UNDER SPATIAL ROTATIONS

- The third iteration does not introduce any new unique operators!
- We just created the operator form for \check{X} :

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \sum_{i=1}^{16} x_i [\check{O}_i(\mathbf{p}, \mathbf{p}', \mathbf{K})] .$$

- \check{X} could be the potential, transition operator with relativistic corrections ...
- The set \mathbb{T} can be extended ...

INVARIANCE UNDER SPATIAL ROTATIONS

- The third iteration does not introduce any new unique operators!
- We just created the operator form for \check{X} :

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \sum_{i=1}^{16} x_i [\check{O}_i(\mathbf{p}, \mathbf{p}', \mathbf{K})] .$$

- \check{X} could be the potential, transition operator with relativistic corrections ...
- The set \mathbb{T} can be extended ...

INVARIANCE UNDER SPATIAL ROTATIONS

- The third iteration does not introduce any new unique operators!
- We just created the operator form for \check{X} :

$$\langle \mathbf{p}'\mathbf{K} | \check{X} | \mathbf{p}\mathbf{K} \rangle = \sum_{i=1}^{16} x_i [\check{O}_i(\mathbf{p}, \mathbf{p}', \mathbf{K})] .$$

- \check{X} could be the potential, transition operator with relativistic corrections ...
- The set \mathbb{T} can be extended ...

ADDING ADDITIONAL SYMMETRIES

- We can use a simple symmetrization procedure.
- Let \mathbb{D} be a grup of transformations constructed from **parity, time reversal, Hermitian conjugate and two particle exchange**.
- A symmetric operator is obtained using:

$$\check{X} \rightarrow \sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}.$$

- Applying any $\check{T} \in \mathbb{D}$ to $\sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}$ returns the same operator.

ADDING ADDITIONAL SYMMETRIES

- We can use a simple symmetrization procedure.
- Let \mathbb{D} be a grup of transformations constructed from **parity, time reversal, Hermitian conjugate and two particle exchange**.
- A symmetric operator is obtained using:

$$\check{X} \rightarrow \sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}.$$

- Applying any $\check{T} \in \mathbb{D}$ to $\sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}$ returns the same operator.

ADDING ADDITIONAL SYMMETRIES

- We can use a simple symmetrization procedure.
- Let \mathbb{D} be a grup of transformations constructed from **parity, time reversal, Hermitian conjugate and two particle exchange**.
- A symmetric operator is obtained using:

$$\check{X} \rightarrow \sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}.$$

- Applying any $\check{T} \in \mathbb{D}$ to $\sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}$ returns the same operator.

ADDING ADDITIONAL SYMMETRIES

- We can use a simple symmetrization procedure.
- Let \mathbb{D} be a grup of transformations constructed from **parity, time reversal, Hermitian conjugate and two particle exchange**.
- A symmetric operator is obtained using:

$$\check{X} \rightarrow \sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}.$$

- Applying any $\check{T} \in \mathbb{D}$ to $\sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}$ returns the same operator.

ADDING ADDITIONAL SYMMETRIES

- We can use a simple symmetrization procedure.
- Let \mathbb{D} be a grup of transformations constructed from **parity, time reversal, Hermitian conjugate and two particle exchange**.
- A symmetric operator is obtained using:

$$\check{X} \rightarrow \sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}.$$

- Applying any $\check{T} \in \mathbb{D}$ to $\sum_{\check{T} \in \mathbb{D}} \check{T} \check{X}$ returns the same operator.

ADDING ADDITIONAL SYMMETRIES

- If this is done carefully [*Eur. Phys. J. A* 52:188 (2016)], a new general form for operators that have rotation invariance and are symmetric with respect to \mathbb{D} can be constructed.
- Additional symmetry conditions on the scalar functions appear.
- The problem becomes more complicated if there are three particles involved [*Phys. Rev. C* 87,054007 (2013)] . . .

ADDING ADDITIONAL SYMMETRIES

- If this is done carefully [*Eur. Phys. J. A* 52:188 (2016)], a new general form for operators that have rotation invariance and are symmetric with respect to \mathbb{D} can be constructed.
- Additional symmetry conditions on the scalar functions appear.
- The problem becomes more complicated if there are three particles involved [*Phys. Rev. C* 87,054007 (2013)] . . .

ADDING ADDITIONAL SYMMETRIES

- If this is done carefully [*Eur. Phys. J. A* 52:188 (2016)], a new general form for operators that have rotation invariance and are symmetric with respect to \mathbb{D} can be constructed.
- Additional symmetry conditions on the scalar functions appear.
- The problem becomes more complicated if there are three particles involved [*Phys. Rev. C* 87,054007 (2013)] . . .

ADDING ADDITIONAL SYMMETRIES

- If this is done carefully [*Eur. Phys. J. A* 52:188 (2016)], a new general form for operators that have rotation invariance and are symmetric with respect to \mathbb{D} can be constructed.
- Additional symmetry conditions on the scalar functions appear.
- The problem becomes more complicated if there are three particles involved [*Phys. Rev. C* 87,054007 (2013)] . . .

NUCLEON DEUTERON SCATTERING

- N-d elastic scattering and breakup description via the 3N Faddeev equation

$$\begin{aligned}\check{T} &= \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{T}. \\ \check{P} &= \check{P}_{12}\check{P}_{23} + \check{P}_{13}\check{P}_{23}.\end{aligned}$$

- Use only first order terms:

$$\check{T} = \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{G}_0\check{P}\check{t}\check{P} + \dots \approx \check{t}\check{P}.$$

- Calculate observables in the breakup channel ($\langle \phi_o |$ - three free nucleons, $|\phi\rangle$ - deuteron and free nucleon):

$$\langle \phi_o | \check{u}_0 | \phi \rangle = \langle \phi_o | (1 + \check{P})\check{t}\check{P} | \phi \rangle.$$

- Calculate observables in the elastic channel:

$$\langle \phi' | \check{u} | \phi \rangle = \langle \phi' | \check{P}\check{G}_0^{-1} + \check{P}\check{t}\check{P} | \phi \rangle.$$

NUCLEON DEUTERON SCATTERING

- N-d elastic scattering and breakup description via the 3N Faddeev equation

$$\begin{aligned}\check{T} &= \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{T}. \\ \check{P} &= \check{P}_{12}\check{P}_{23} + \check{P}_{13}\check{P}_{23}.\end{aligned}$$

- Use only first order terms:

$$\check{T} = \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{G}_0\check{P}\check{t}\check{P} + \dots \approx \check{t}\check{P}.$$

- Calculate observables in the breakup channel ($\langle \phi_o |$ - three free nucleons, $|\phi\rangle$ - deuteron and free nucleon):

$$\langle \phi_o | \check{u}_0 | \phi \rangle = \langle \phi_o | (1 + \check{P})\check{t}\check{P} | \phi \rangle.$$

- Calculate observables in the elastic channel:

$$\langle \phi' | \check{u} | \phi \rangle = \langle \phi' | \check{P}\check{G}_0^{-1} + \check{P}\check{t}\check{P} | \phi \rangle.$$

NUCLEON DEUTERON SCATTERING

- N-d elastic scattering and breakup description via the 3N Faddeev equation

$$\begin{aligned}\check{T} &= \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{T}. \\ \check{P} &= \check{P}_{12}\check{P}_{23} + \check{P}_{13}\check{P}_{23}.\end{aligned}$$

- Use only first order terms:

$$\check{T} = \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{G}_0\check{P}\check{t}\check{P} + \dots \approx \check{t}\check{P}.$$

- Calculate observables in the breakup channel ($\langle \phi_o |$ - three free nucleons, $|\phi\rangle$ - deuteron and free nucleon):

$$\langle \phi_o | \check{u}_0 | \phi \rangle = \langle \phi_o | (1 + \check{P})\check{t}\check{P} | \phi \rangle.$$

- Calculate observables in the elastic channel:

$$\langle \phi' | \check{u} | \phi \rangle = \langle \phi' | \check{P}\check{G}_0^{-1} + \check{P}\check{t}\check{P} | \phi \rangle.$$

NUCLEON DEUTERON SCATTERING

- N-d elastic scattering and breakup description via the 3N Faddeev equation

$$\begin{aligned}\check{T} &= \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{T}. \\ \check{P} &= \check{P}_{12}\check{P}_{23} + \check{P}_{13}\check{P}_{23}.\end{aligned}$$

- Use only first order terms:

$$\check{T} = \check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{P} + \check{t}\check{G}_0\check{P}\check{t}\check{G}_0\check{P}\check{t}\check{P} + \dots \approx \check{t}\check{P}.$$

- Calculate observables in the breakup channel ($\langle \phi_o |$ - three free nucleons, $|\phi\rangle$ - deuteron and free nucleon):

$$\langle \phi_o | \check{u}_0 | \phi \rangle = \langle \phi_o | (1 + \check{P})\check{t}\check{P} | \phi \rangle.$$

- Calculate observables in the elastic channel:

$$\langle \phi' | \check{u} | \phi \rangle = \langle \phi' | \check{P}\check{G}_0^{-1} + \check{P}\check{t}\check{P} | \phi \rangle.$$

NUCLEON DEUTERON SCATTERING

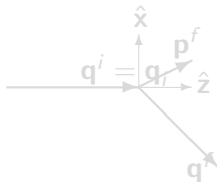
- Compare 3D approach and “battle tested” PWD approach.

ELASTIC SCATTERING:



- Initially the neutron: q_i . In the final state, the neutron: q_f .
- Scattering parametrized by $\theta_{c.m.}$.

BREAKUP:



- In the final state the Jacobi momenta: p^f and q^f .
- Scattering parametrized by the kinematic curve parameter S : $p^f(S), q^f(S)$.

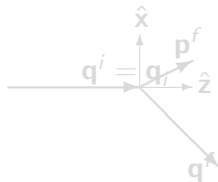
NUCLEON DEUTERON SCATTERING

- Compare 3D approach and “battle tested” PWD approach.

ELASTIC SCATTERING:



BREAKUP:



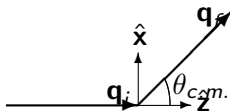
- Initially the neutron: q_i . In the final state, the neutron: q_f .
- Scattering parametrized by $\theta_{c.m.}$.

- In the final state the Jacobi momenta: p^f and q^f .
- Scattering parametrized by the kinematic curve parameter S : $p^f(S), q^f(S)$.

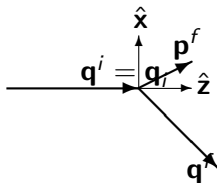
NUCLEON DEUTERON SCATTERING

- Compare 3D approach and “battle tested” PWD approach.

ELASTIC SCATTERING:



BREAKUP:



- Initially the neutron: \mathbf{q}_i . In the final state, the neutron: \mathbf{q}_f .
- Scattering parametrized by $\theta_{c.m.}$.

- In the final state the Jacobi momenta: \mathbf{p}^f and \mathbf{q}^f .
- Scattering parametrized by the kinematic curve parameter S : $\mathbf{p}^f(S), \mathbf{q}^f(S)$.

NUCLEON DEUTERON SCATTERING

- Results for breakup [Eur. Phys. J. A 51:132 (2015)].
- Deuteron and nucleon vector analyzing powers (A_y^d , A_y^N) and the deuteron tensor analyzing powers (A_{xx} , A_{yy} , A_{zz}) LAB energy 190 MeV.
- Solid line - 3D results.
- The dashed-dotted, dotted and dashed lines - PWD results with max. total angular momentum 21/2, 23/2, 25/2 and max. 2 – 3 angular momentum 8.

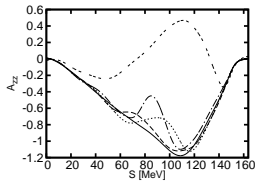
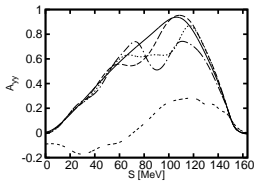
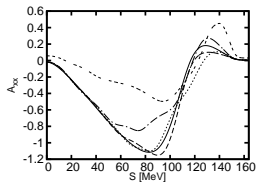
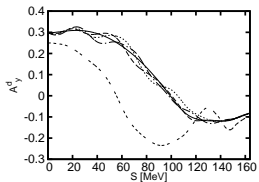
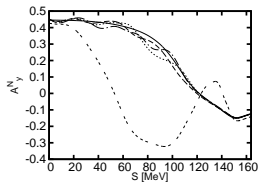
NUCLEON DEUTERON SCATTERING

- Results for breakup [Eur. Phys. J. A 51:132 (2015)].
- Deuteron and nucleon vector analyzing powers (A_y^d , A_y^N) and the deuteron tensor analyzing powers (A_{xx} , A_{yy} , A_{zz}) LAB energy 190 MeV.
- Solid line - 3D results.
- The dashed-dotted, dotted and dashed lines - PWD results with max. total angular momentum 21/2, 23/2, 25/2 and max. 2 – 3 angular momentum 8.

NUCLEON DEUTERON SCATTERING

- Results for breakup [Eur. Phys. J. A 51:132 (2015)].
- Deuteron and nucleon vector analyzing powers (A_y^d , A_y^N) and the deuteron tensor analyzing powers (A_{xx} , A_{yy} , A_{zz}) LAB energy 190 MeV.
- Solid line - 3D results.
- The dashed-dotted, dotted and dashed lines - PWD results with max. total angular momentum 21/2, 23/2, 25/2 and max. 2 – 3 angular momentum 8.

NUCLEON DEUTERON SCATTERING



FULL 3D CALCULATION

- We can construct the operator form of \check{T} but this form contains too many parameters.
- Construct the operator form of $\check{T} | \phi \rangle$ under using similar methods - this is under construction.
- Calculate the solution using similar methods as with the two nucleon transition operator.

FULL 3D CALCULATION

- We can construct the operator form of \check{T} but this form contains too many parameters.
- Construct the operator form of $\check{T} | \phi \rangle$ under using similar methods - this is under construction.
- Calculate the solution using similar methods as with the two nucleon transition operator.

FULL 3D CALCULATION

- We can construct the operator form of \check{T} but this form contains too many parameters.
- Construct the operator form of $\check{T} | \phi \rangle$ under using similar methods - this is under construction.
- Calculate the solution using similar methods as with the two nucleon transition operator.

FULL 3D CALCULATION

- We can construct the operator form of \check{T} but this form contains too many parameters.
- Construct the operator form of $\check{T} | \phi \rangle$ under using similar methods - this is under construction.
- Calculate the solution using similar methods as with the two nucleon transition operator.

- First order results for neutron deuteron scattering suggest that the 3D approach can be used to achieve convergence at higher energies.
- There is a necessity to construct new general operator forms.
- Constructing $\check{T} | \phi \rangle$ can lead to efficient calculations.
- Possibility to add relativistic corrections to the calculations.

THANK YOU

The project was financed from the resources of the National Science Center (Poland) under grants No. DEC-2013/11/N/ST2/03733 and DEC-2013/10/M/ST2/00420. Some of the numerical work was performed at JSC Jülich.